

Groth's algorithm to detect the possible presence of landmines using changes in the reflection of plants

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Abstract: Post-conflict reconstruction includes the removal of land mines and remnants of war. The CSIR conducted field experiments to determine the impact of TNT in the soil on plants as a possible means to detect landmines. All the leaf clip readings were done using a spectrometer to determine reflection and absorption of light at one micrometre intervals between 350 to 2500 micrometre. Laboratory analysis such as UPLC qTOF MS indicated that the TNT have an influence on the plants. Several indices such as Modified Red Edge Normalized Difference Vegetation Index (mNDVI705), Red Edge Position (REP) and Moisture Stress Index (MSI) did not show any significant differences between control plants and experimental plants with different TNT concentrations. Groth's pattern matching algorithm designed to match several photographs of the same part of the universe. A set of triangles using dominant stars are created for each photograph and matched using an error band. If the selected triangles from the two photographs fit within the error band, then they are from the same section of the universe. Bands for the Pléiades instruments were simulated using the data from the spectrometer for each plant. The reflectance value of the band and the normalised midpoint wavelength of each Pléiades band were used to construct the triangles. The control plant triangle is then matched with the experimental plant and if the triangles do not match, then the effect of TNT on the plant is significant. The initial results with the control plants and experimental plants are positive.

Keywords: landmines, detection, clearing operations, reflectance, simulation

1. Introduction

1.1 Background

Landmines are explosive weapons used in conflict situations. They are intentionally hidden and are used as "booby-traps", with the aim of damaging, disabling or killing what or whoever triggered it, slowing down the progress of troops and vehicles (Keely: 2003). The two common types of landmines are anti-personnel (AP) and anti-tank mines (AT). The key components of both versions are the same: a casing, a firing mechanism or trigger, and an explosive charge, often 2,4,6-trinitrotoluene (TNT) (Robledo, *et al.*, 2009; Makki, *et al.*, 2017).

They are placed randomly, and unfortunately, after the resolution of the conflict, any landmines laid are usually not recovered. These abandoned minefields not only pose a serious threat to people who come into immediate contact with them, but they could also prohibit access to critical

resources, such as water or medical services (Oppong and Kalipeni: 2005; Makki, *et al.*, 2017). If an individual triggers a landmine, the consequences can be severe. Damage to the muscular or skeletal system of the individual can render him/her disabled and may even lead to death. These problems also occur with unexploded ordnance (UXO), abandoned explosive ordnance (AXO) improvised explosive devices (IEDs) and other explosive remnants (UNMAS 2019a).

Because of the threat landmines in particular pose to civilian society, efforts to find and safely remove landmines are often made by organisations such as the United Nations Mine Action Service (UNMAS)¹ and the Geneva International Centre for Humanitarian Demining (GICHD)². It is a tedious process, with many risks, and extremely high costs.

Several methods of detection have been used such as prodders, metal detectors, ground penetrating radar, dogs, African giant rats, thermal neutron activators, and hyperspectral remote sensing methods (Bruschini and

¹ <https://www.unmas.org/>

² <https://www.gichd.org/>

The aim is to find an algorithm that could be used to indicate possibility of landmine (or explosive) presence using off-the-shelf data such as those from high resolution satellite imagery and aerial imagery.

1.4 Groth's algorithm

Groth's algorithm is a pattern-matching algorithm using 2D coordinate lists of listed bright stars that occur in two or more photographs of the same region in the sky. These coordinates are used to establish a list of triangles for the different photographs. The coordinates are transformed to create a single dimensionless coordinate system that is applicable to the different photographs (Groth, 1986). The methodology followed by Groth (1986) is first to establish the points (stars) that need to be matched; generate the lists of triangles using the identified points; match the triangles; reduce the number of false matches; assign the matched points using the matched triangles; and the last step is repeat the process to eliminate possible spurious assignments which are matches using different points are used that are listed but are not in common with the pre-selected list of bright stars.

Each triangle has a set of three vertices (1, 2, and 3) and the corresponding coordinate pairs (x_1, y_1) ; (x_2, y_2) ; and (x_3, y_3) .

The tolerance is similar to an error band in which it is acceptable to match two triangles: if the triangles are outside this tolerance, then they do not match. Groth (1986) gave the tolerance (ϵ) of 0,001 as a default value. This value was used in this study. All the equations listed below are by Groth (1986). Any other equations will be referenced individually.

To be able to match the triangles (A and B) one needs to calculate the ratio (R) of two vertices namely 2 and 3 and the cosine (C) of the angle at vertex 1.

$$R = r_3/r_2 \quad (1)$$

where,

$$r_3 = \sqrt{\Delta x_3^2 + \Delta y_3^2}, \Delta x_3 = x_3 - x_1, \Delta y_3 = y_3 - y_1 \quad (2)$$

$$r_2 = \sqrt{\Delta x_2^2 + \Delta y_2^2}, \Delta x_2 = x_2 - x_1, \Delta y_2 = y_2 - y_1 \quad (3)$$

The tolerance in R is calculated as follows:

$$t_R^2 = 2R^2 \epsilon^2 \left(\frac{1}{r_3^2} - \frac{C}{r_3 r_2} + \frac{1}{r_2^2} \right) \quad (4)$$

C is the cosine of the angle at vertex 1.

$$C = 2S^2 \epsilon^2 (\Delta x_3 \Delta x_2 + \Delta y_3 \Delta y_2) / r_3 r_2 \quad (5)$$

and the tolerance in C is:

$$t_C^2 = 2S^2 \epsilon^2 \left(\frac{1}{r_3^2} - \frac{C}{r_3 r_2} + \frac{1}{r_2^2} \right) + 3C^2 \epsilon^2 \left(\frac{1}{r_3^2} - \frac{C}{r_3 r_2} + \frac{1}{r_2^2} \right) \quad (6)$$

where S is the sine of the angle at vertex 1.

These values are used to match the triangles, or in our study to determine whether the triangles do not match to

indicate the effect of TNT on the trees (that is, the reverse Groth's algorithm). The matching is done whenever:

$$(R_A - R_B)^2 < t_{RA}^2 + t_{RB}^2 \quad (7)$$

and

$$(C_A - C_B)^2 < t_{CA}^2 + t_{CB}^2 \quad (8)$$

where A in this study is the triangle of the control tree and B are the trees that have been contaminated with TNT. If one of the conditions in equations 7 and 8 are not satisfied, it means that the triangles cannot be matched, and it indicates in this study that the TNT had a significant impact on the trees. Please note that this algorithm indicates an impact but not the magnitude thereof.

The advantage of using Groth's algorithm is that it is insensitive to coordinate translations, rotation, inversion, etc. and tolerant to random errors and distortions (Groth, 1986). Figure 2 illustrates the concept.

Applications of Groth's algorithm outside of astronomy are in ecology where it is used to match different photographs of whale sharks to determine if it is the same whale shark which aids in the tracking of these whale sharks. Another application is to use it on photographs showing the spot patterns around the mouth and nose of a polar bear as shown in figure 3 (NASA, 2012). The use of Groth's Algorithm in ecology gave the idea to test it on determining the impact of TNT on plants and the possibility to use it to detect landmines especially after many years after the war ended.

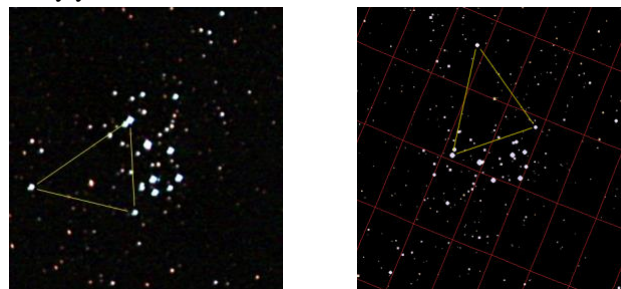


Photo 1

Photo 2

Figure 2. Matching the two photographs of the same region of the sky (Marszalek and Rokita, 2004).



Figure 3. Spots on a whale shark (NASA, 2012).

2. Methodology

The methodology to determine the impact of TNT on plants using Groth's algorithm was done in two stages. The first stage was to average the readings over time and to simulate the Pléiades bands. The second step was to use Groth's algorithm in reverse, meaning if the triangles did not match, then there is a detectable impact of TNT on the plant.

2.1 Determining the Pléiades bands

To develop the triangles, the captured data over the period (2013 to 2016) was averaged to get a single value for each tree for each interval. The Cape Holly tree data was only for 2013 and is included to determine whether the TNT had an impact or not. The authors then used the Pléiades band intervals to determine the reflectance value per band. It could be that certain wavelengths within a band could have a higher weight than other, but this could not be determined³ and it was decided to use the average for each band. An example of the simulated bands is shown in table 1.

Pleiades bands	Tree: White Stinkwood	mg TNT/kg soil		
	Range	Control	30mgTNT	300mgTNT
	430 -550	0,087724	0,098375	0,093461
	490 - 610	0,134263	0,150571	0,139979
	600 - 720	0,125150	0,143009	0,132764
NIR	750 - 950	0,491961	0,491130	0,500647

Pleiades bands	Tree: White Stinkwood	mg TNT/kg soil		
	Range	600mgTNT	1200mgTNT	5000mgTNT
	430 -550	0,076829	0,082864	0,088414
	490 - 610	0,108559	0,123269	0,114430
	600 - 720	0,109525	0,119470	0,105791
NIR	750 - 950	0,458533	0,492476	0,474511

Table 1. Simulated reflectance values for the four Pléiades bands.

2.2 The non-matching of the triangles

The assumption is that the triangles of the control trees do not match the triangles of the contaminated trees which is to the reverse of the original design of Groth's algorithm. The reflectance value of the trees in the Pléiades bands were used as the one set of the coordinate pair, whereas the midpoint frequency was used as the second set of the coordinate pair. The midpoint frequency was normalised to be between 0 and 1 using frequency divided by 950, which is the longest wavelength of the four Pléiades bands used. Table 2 shows the normalised midpoints for each Pléiades band.

Colour	Range	Midpoint	Normalised
	430 -550	490	0,5158
	490 - 610	550	0,5789
	600 - 720	660	0,6947
NIR	750 - 950	850	0,8947

³ S Cullen, personal communication, 2022.

Table 2. Normalised midpoint values for each Pléiades band.

The following four triangle pairs were created namely:

- Blue-Green-Red
- Blue-Red-NIR
- Blue-Green-NIR
- Green-Red-NIR

The control tree was chosen as the first triangle (A) which is compared against the triangles (B) for each of the different TNT concentrations contaminating the tree. Figure 3 shows an example of the triangles created using the normalised midpoints and reflectance of the bands for each tree.

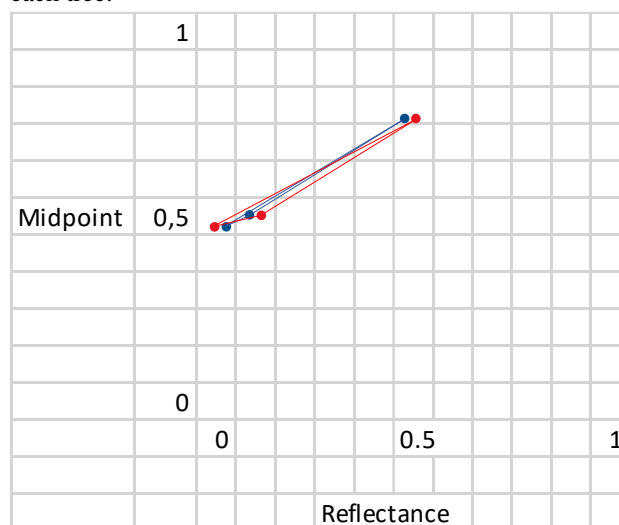


Figure 3. Constructing the triangles (Red – control tree and blue – tree contaminated with 30mg TNT/kg soil).

Equations 1 to 8 were used in an MS Excel spreadsheet for each tree species to determine the impact of TNT on the trees. The results of the matching of the triangles are discussed in the next section.

3. Results

The results of matching the triangles are shown graphically in figures 4 to 7. The columns are the six trees that were used in the experiment and the rows represent the controls and levels of contamination for each tree species. The triangle bands are shown in the top row of the figure.

- Using Pléiades imagery of the same area of the field experiment using the ASD readings as a control to verify the process.
- Apply the methodology on other sources of imagery such as Landsat TM, SPOT, and imagery from airborne platforms.

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